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While there are many books on advanced control for specialists, there are few that present these topics for nonspecialists. Assuming only a basic knowledge of automatic control and signals and systems, *Optimal and Robust Control: Advanced Topics with MATLAB®* offers a straightforward, self-contained handbook of advanced topics and tools in automatic control. Techniques for Controlling System Performance in the Presence of Uncertainty The book deals with advanced automatic control techniques, paying particular attention to robustness—the ability to guarantee stability in the presence of uncertainty. It explains advanced techniques for handling uncertainty and optimizing the control loop. It also details analytical strategies for obtaining reduced order models. The authors then propose using the Linear Matrix Inequalities (LMI) technique as a unifying tool to solve many types of advanced control problems. Topics covered include: LQR and H-infinity approaches Kalman and singular value decomposition Open-loop balancing and reduced order models Closed-loop balancing Passive systems and bounded-real systems Criteria for stability control This easy-to-read text presents the essential theoretical background and provides numerous examples and MATLAB exercises to help the reader efficiently acquire new skills. Written for electrical, electronic, computer science, space, and automation engineers interested in automatic control, this book can also be used for self-study or for a one-semester course in robust control.

This is the eBook of the printed book and may not include any media, website access codes, or print supplements that may come packaged with the bound book. For senior-level or first-year graduate-level courses in control analysis and design, and related courses within engineering, science, and management. *Feedback Control of Dynamic Systems, Sixth Edition* is perfect for practicing control engineers who wish to maintain their skills. This revision of a top-selling textbook on feedback control with the associated web site, FPE6e.com, provides greater instructor flexibility and student readability. Chapter 4 on A First Analysis of Feedback has been substantially rewritten to present the material in a more logical and effective manner. A new case study on biological control introduces an important new area to the students, and each chapter now includes a historical perspective to illustrate the origins of the field. As in earlier editions, the book has been updated so that solutions are based on the latest versions of MATLAB and SIMULINK. Finally, some of the more exotic topics have been moved to the web site.

There has been much excitement over the emergence of new mathematical techniques for the analysis and control of nonlinear systems. In addition, great technological advances have bolstered the impact of analytic advances and produced many new problems and applications which are nonlinear in an essential way. This book lays out in a concise mathematical framework the tools and methods of analysis which underlie this diversity of applications.

For a first course on nonlinear control that can be taught in one semester λ This book emerges from the award-winning book, *Nonlinear Systems*, but has a distinctly different mission and organization. While *Nonlinear Systems* was intended as a reference and a text on nonlinear system analysis and its application to control, this streamlined book is intended as a text for a first course on nonlinear control. In *Nonlinear Control*, author Hassan K. Khalil employs a writing style that is intended to make the book accessible to a wider audience without compromising the rigor of the presentation. λ Teaching and Learning Experience This program will provide a better teaching and learning experience—for you and your students. It will help: Provide an Accessible Approach to Nonlinear Control: This streamlined book is intended as a text for a first course on nonlinear control that can be taught in one semester. Support Learning: Over 250 end-of-chapter exercises give students plenty of opportunities to put theory into action.

Applied Nonlinear Control Pearson Education Nonlinear Control Prentice Hall For a first course on nonlinear control that can be taught in one semester λ This book emerges from the award-winning book, *Nonlinear Systems*, but has a distinctly different mission and organization. While *Nonlinear Systems* was intended as a reference and a text on nonlinear system analysis and its application to control, this streamlined book is intended as a text for a first course on nonlinear control. In *Nonlinear Control*, author Hassan K. Khalil employs a writing style that is intended to make the book accessible to a wider audience without compromising the rigor of the presentation. λ Teaching and Learning Experience This program will provide a better teaching and learning experience—for you and your students. It will help: Provide an Accessible Approach to Nonlinear Control: This streamlined book is intended as a text for a first course on nonlinear control that can be taught in one semester. Support Learning: Over 250 end-of-chapter exercises give students plenty of opportunities to put theory into action. Student Solutions Manual for Nonlinear Dynamics and Chaos, 2nd edition CRC Press This official Student Solutions Manual includes solutions to the odd-numbered exercises featured in the second edition of Steven Strogatz's classic text *Nonlinear Dynamics and Chaos: With Applications to Physics, Biology, Chemistry, and Engineering*. The textbook and accompanying Student Solutions Manual are aimed at newcomers to nonlinear dynamics and chaos, especially students taking a first course in the subject. Complete with graphs and worked-out solutions, this manual demonstrates techniques for students to analyze differential equations, bifurcations, chaos, fractals, and other subjects Strogatz explores in his popular book. Introduction to Applied Nonlinear Dynamical Systems and Chaos Springer Science & Business Media This introduction to applied nonlinear dynamics and chaos places emphasis on teaching the techniques and ideas that will enable students to take specific dynamical systems and obtain some quantitative information about their behavior. The new edition has been updated and extended throughout, and contains a detailed glossary of terms. From the reviews: "Will serve as one of the most eminent introductions to the geometric theory of dynamical systems." --- Monatshefte für Mathematik Nonlinear Dynamics and Chaos With Applications to Physics, Biology, Chemistry, and Engineering CRC Press This textbook is aimed at newcomers to nonlinear dynamics and chaos, especially students taking a first course in the subject. The presentation stresses analytical

methods, concrete examples, and geometric intuition. The theory is developed systematically, starting with first-order differential equations and their bifurcations, followed by phase plane analysis, limit cycles and their bifurcations, and culminating with the Lorenz equations, chaos, iterated maps, period doubling, renormalization, fractals, and strange attractors. Differential Dynamical Systems, Revised Edition SIAM Differential equations are the basis for models of any physical systems that exhibit smooth change. This book combines much of the material found in a traditional course on ordinary differential equations with an introduction to the more modern theory of dynamical systems. Applications of this theory to physics, biology, chemistry, and engineering are shown through examples in such areas as population modeling, fluid dynamics, electronics, and mechanics. Differential Dynamical Systems begins with coverage of linear systems, including matrix algebra; the focus then shifts to foundational material on nonlinear differential equations, making heavy use of the contraction-mapping theorem. Subsequent chapters deal specifically with dynamical systems concepts? flow, stability, invariant manifolds, the phase plane, bifurcation, chaos, and Hamiltonian dynamics. This new edition contains several important updates and revisions throughout the book. Throughout the book, the author includes exercises to help students develop an analytical and geometrical understanding of dynamics. Many of the exercises and examples are based on applications and some involve computation; an appendix offers simple codes written in Maple?, Mathematica?, and MATLAB? software to give students practice with computation applied to dynamical systems problems. Differential Equations and Dynamical Systems Springer Science & Business Media Mathematics is playing an ever more important role in the physical and biological sciences, provoking a blurring of boundaries between scientific disciplines and a resurgence of interest in the modern as well as the classical techniques of applied mathematics. This renewal of interest, both in research and teaching, has led to the establishment of the series: Texts in Applied Mathematics (TAM). The development of new courses is a natural consequence of a high level of excitement on the research frontier as newer techniques, such as numerical and symbolic computer systems, dynamical systems, and chaos, mix with and reinforce the traditional methods of applied mathematics. Thus, the purpose of this textbook series is to meet the current and future needs of these advances and encourage the teaching of new courses. TAM will publish textbooks suitable for use in advanced undergraduate and beginning graduate courses, and will complement the Applied Mathematical Sciences (AMS) series, which will focus on advanced textbooks and research level monographs. Preface to the Second Edition This book covers those topics necessary for a clear understanding of the qualitative theory of ordinary differential equations and the concept of a dynamical system. It is written for advanced undergraduates and for beginning graduate students. It begins with a study of linear systems of ordinary differential equations, a topic already familiar to the student who has completed a first course in differential equations. Feedback Systems Princeton University Press The essential introduction to the principles and applications of feedback systems—now fully revised and expanded This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of *Feedback Systems* is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots Provides exercises at the end of every chapter Comes with an electronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for researchers seeking a self-contained resource on control theory Design of Nonlinear Control Systems with the Highest Derivative in Feedback World Scientific This unique book presents an analytical uniform design methodology of continuous-time or discrete-time nonlinear control system design which guarantees desired transient performances in the presence of plant parameter variations and unknown external disturbances. All results are illustrated with numerical simulations, their practical importance is highlighted, and they may be used for real-time control system design in robotics, mechatronics, chemical reactors, electrical and electro-mechanical systems as well as aircraft control systems. The book is easy reading and is suitable for teaching. Nonlinear Dynamical Systems and Control A Lyapunov-Based Approach Princeton University Press Nonlinear Dynamical Systems and Control presents and develops an extensive treatment of stability analysis and control design of nonlinear dynamical systems, with an emphasis on Lyapunov-based methods. Dynamical system theory lies at the heart of mathematical sciences and engineering. The application of dynamical systems has crossed interdisciplinary boundaries from chemistry to biochemistry to chemical kinetics, from medicine to biology to population genetics, from economics to sociology to psychology, and from physics to mechanics to engineering. The increasingly complex nature of engineering systems requiring feedback control to obtain a desired system behavior also gives rise to dynamical systems. Wassim Haddad and Vijay Sekhar Chellaboina provide an exhaustive treatment of nonlinear systems theory and control using the highest standards of exposition and rigor. This graduate-level textbook goes well beyond standard treatments by developing Lyapunov stability theory, partial stability, boundedness, input-to-state stability, input-output stability, finite-time stability, semistability, stability of sets and periodic orbits, and stability theorems via vector Lyapunov functions. A complete and thorough treatment of dissipativity theory, absolute stability theory, stability of feedback systems, optimal control, disturbance rejection control, and robust control for nonlinear dynamical systems is also given. This book is an indispensable resource for applied mathematicians, dynamical systems theorists, control theorists, and engineer-

s. Nonlinear Dynamics and Chaos with Student Solutions Manual With Applications to Physics, Biology, Chemistry, and Engineering, Second Edition CRC Press This textbook is aimed at newcomers to nonlinear dynamics and chaos, especially students taking a first course in the subject. The presentation stresses analytical methods, concrete examples, and geometric intuition. The theory is developed systematically, starting with first-order differential equations and their bifurcations, followed by phase plane analysis, limit cycles and their bifurcations, and culminating with the Lorenz equations, chaos, iterated maps, period doubling, renormalization, fractals, and strange attractors. Fuzzy Algorithms for Control Springer Science & Business Media Fuzzy Algorithms for Control gives an overview of the research results of a number of European research groups that are active and play a leading role in the field of fuzzy modeling and control. It contains 12 chapters divided into three parts. Chapters in the first part address the position of fuzzy systems in control engineering and in the AI community. State-of-the-art surveys on fuzzy modeling and control are presented along with a critical assessment of the role of these methodologists in control engineering. The second part is concerned with several analysis and design issues in fuzzy control systems. The analytical issues addressed include the algebraic representation of fuzzy models of different types, their approximation properties, and stability analysis of fuzzy control systems. Several design aspects are addressed, including performance specification for control systems in a fuzzy decision-making framework and complexity reduction in multivariable fuzzy systems. In the third part of the book, a number of applications of fuzzy control are presented. It is shown that fuzzy control in combination with other techniques such as fuzzy data analysis is an effective approach to the control of modern processes which present many challenges for the design of control systems. One has to cope with problems such as process nonlinearity, time-varying characteristics for incomplete process knowledge. Examples of real-world industrial applications presented in this book are a blast furnace, a lime kiln and a solar plant. Other examples of challenging problems in which fuzzy logic plays an important role and which are included in this book are mobile robotics and aircraft control. The aim of this book is to address both theoretical and practical subjects in a balanced way. It will therefore be useful for readers from the academic world and also from industry who want to apply fuzzy control in practice. Signals and Systems using MATLAB Academic Press Signals and Systems Using MATLAB, Third Edition, features a pedagogically rich and accessible approach to what can commonly be a mathematically dry subject. Historical notes and common mistakes combined with applications in controls, communications and signal processing help students understand and appreciate the usefulness of the techniques described in the text. This new edition features more end-of-chapter problems, new content on two-dimensional signal processing, and discussions on the state-of-the-art in signal processing. Introduces both continuous and discrete systems early, then studies each (separately) in-depth Contains an extensive set of worked examples and homework assignments, with applications for controls, communications, and signal processing Begins with a review on all the background math necessary to study the subject Includes MATLAB® applications in every chapter Applied Linear Algebra Springer This textbook develops the essential tools of linear algebra, with the goal of imparting technique alongside contextual understanding. Applications go hand-in-hand with theory, each reinforcing and explaining the other. This approach encourages students to develop not only the technical proficiency needed to go on to further study, but an appreciation for when, why, and how the tools of linear algebra can be used across modern applied mathematics. Providing an extensive treatment of essential topics such as Gaussian elimination, inner products and norms, and eigenvalues and singular values, this text can be used for an in-depth first course, or an application-driven second course in linear algebra. In this second edition, applications have been updated and expanded to include numerical methods, dynamical systems, data analysis, and signal processing, while the pedagogical flow of the core material has been improved. Throughout, the text emphasizes the conceptual connections between each application and the underlying linear algebraic techniques, thereby enabling students not only to learn how to apply the mathematical tools in routine contexts, but also to understand what is required to adapt to unusual or emerging problems. No previous knowledge of linear algebra is needed to approach this text, with single-variable calculus as the only formal prerequisite. However, the reader will need to draw upon some mathematical maturity to engage in the increasing abstraction inherent to the subject. Once equipped with the main tools and concepts from this book, students will be prepared for further study in differential equations, numerical analysis, data science and statistics, and a broad range of applications. The first author's text, Introduction to Partial Differential Equations, is an ideal companion volume, forming a natural extension of the linear mathematical methods developed here. Solutions Manual to accompany An Introduction to Numerical Methods and Analysis John Wiley & Sons A solutions manual to accompany An Introduction to Numerical Methods and Analysis, Second Edition An Introduction to Numerical Methods and Analysis, Second Edition reflects the latest trends in the field, includes new material and revised exercises, and offers a unique emphasis on applications. The author clearly explains how to both construct and evaluate approximations for accuracy and performance, which are key skills in a variety of fields. A wide range of higher-level methods and solutions, including new topics such as the roots of polynomials, spectral collocation, finite element ideas, and Clenshaw-Curtis quadrature, are presented from an introductory perspective, and the Second Edition also features: ulstyle="line-height: 25px; margin-left: 15px; margin-top: 0px; font-family: Arial; font-size: 13px;" Chapters and sections that begin with basic, elementary material followed by gradual coverage of more advanced material Exercises ranging from simple hand computations to challenging derivations and minor proofs to programming exercises Widespread exposure and utilization of MATLAB® An appendix that contains proofs of various theorems and other material Differential Equation Models Springer Science & Business Media The purpose of this four volume series is to make available for college teachers and students samples of important and realistic applications of mathematics which can be covered in undergraduate programs. The goal is to provide illustrations of how modern mathematics is actually employed to solve relevant contemporary problems. Although these independent chapters were prepared primarily for teachers in the general mathematical sciences, they should prove valuable to students, teachers, and research scientists in many of the fields of application as well. Prerequisites for each chapter and suggestions for the teacher are provided. Several of these chapters have been tested in a variety of classroom settings, and all have undergone extensive peer review and revision. Illustrations and exercises are included in most chapters. Some units can be covered in one class, whereas others provide sufficient material for a few weeks of class time. Volume 1 contains 23 chapters and deals with differential equations and, in the last four chapters, problems leading to partial differential equations. Applications are taken from medicine, biology, traffic systems and several other fields. The 14 chapters in Volume 2 are devoted mostly to problems arising in political science, but they also address questions appearing in sociology and ecology. Topics covered include voting systems, weighted voting, proportional representation, coalitional values, and committees. The 14 chapters in Volume 3 emphasize discrete mathematical methods such as those which arise in graph theory, combinatorics, and networks. Applied Mechanics Reviews Adaptive Control of Parabolic PDEs Princeton University

Press This book introduces a comprehensive methodology for adaptive control design of parabolic partial differential equations with unknown functional parameters, including reaction-convection-diffusion systems ubiquitous in chemical, thermal, biomedical, aerospace, and energy systems. Andrey Smyshlyaev and Miroslav Krstic develop explicit feedback laws that do not require real-time solution of Riccati or other algebraic operator-valued equations. The book emphasizes stabilization by boundary control and using boundary sensing for unstable PDE systems with an infinite relative degree. The book also presents a rich collection of methods for system identification of PDEs, methods that employ Lyapunov, passivity, observer-based, swapping-based, gradient, and least-squares tools and parameterizations, among others. Including a wealth of stimulating ideas and providing the mathematical and control-systems background needed to follow the designs and proofs, the book will be of great use to students and researchers in mathematics, engineering, and physics. It also makes a valuable supplemental text for graduate courses on distributed parameter systems and adaptive control. Nonlinear Control Systems Springer Science & Business Media The purpose of this book is to present a self-contained description of the fundamentals of the theory of nonlinear control systems, with special emphasis on the differential geometric approach. The book is intended as a graduate text as well as a reference to scientists and engineers involved in the analysis and design of feedback systems. The first version of this book was written in 1983, while I was teaching at the Department of Systems Science and Mathematics at Washington University in St. Louis. This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana-Champaign in 1987, at the Carl-Cranz Gesellschaft in Oberpfaffenhofen in 1987, at the University of California in Berkeley in 1988. In addition to a major rearrangement of the last two Chapters of the first version, this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985. Nonlinear Systems Analysis, Stability, and Control Springer Science & Business Media There has been much excitement over the emergence of new mathematical techniques for the analysis and control of nonlinear systems. In addition, great technological advances have bolstered the impact of analytic advances and produced many new problems and applications which are nonlinear in an essential way. This book lays out in a concise mathematical framework the tools and methods of analysis which underlie this diversity of applications. Nonlinear Systems Analysis, Stability, and Control Springer There has been much excitement over the emergence of new mathematical techniques for the analysis and control of nonlinear systems. In addition, great technological advances have bolstered the impact of analytic advances and produced many new problems and applications which are nonlinear in an essential way. This book lays out in a concise mathematical framework the tools and methods of analysis which underlie this diversity of applications. Introduction to Applied Optimization Springer Science & Business Media This text presents a multi-disciplined view of optimization, providing students and researchers with a thorough examination of algorithms, methods, and tools from diverse areas of optimization without introducing excessive theoretical detail. This second edition includes additional topics, including global optimization and a real-world case study using important concepts from each chapter. Introduction to Applied Optimization is intended for advanced undergraduate and graduate students and will benefit scientists from diverse areas, including engineers. Nonlinear Control Systems II Springer Science & Business Media This eagerly awaited follow-up to Nonlinear Control Systems incorporates recent advances in the design of feedback laws, for the purpose of globally stabilizing nonlinear systems via state or output feedback. The author is one of the most prominent researchers in the field. Feedback Control of Dynamic Systems Pearson Higher Ed This is the eBook of the printed book and may not include any media, website access codes, or print supplements that may come packaged with the bound book. For senior-level or first-year graduate-level courses in control analysis and design, and related courses within engineering, science, and management. Feedback Control of Dynamic Systems, Sixth Edition is perfect for practicing control engineers who wish to maintain their skills. This revision of a top-selling textbook on feedback control with the associated web site, FPE6e.com, provides greater instructor flexibility and student readability. Chapter 4 on A First Analysis of Feedback has been substantially rewritten to present the material in a more logical and effective manner. A new case study on biological control introduces an important new area to the students, and each chapter now includes a historical perspective to illustrate the origins of the field. As in earlier editions, the book has been updated so that solutions are based on the latest versions of MATLAB and SIMULINK. Finally, some of the more exotic topics have been moved to the web site. Nonlinear Systems Pearson New International Edition Pearson For a first-year graduate-level course on nonlinear systems. It may also be used for self-study or reference by engineers and applied mathematicians. The text is written to build the level of mathematical sophistication from chapter to chapter. It has been reorganized into four parts: Basic analysis, Analysis of feedback systems, Advanced analysis, and Nonlinear feedback control. Optimal Control Theory An Introduction Courier Corporation Upper-level undergraduate text introduces aspects of optimal control theory: dynamic programming, Pontryagin's minimum principle, and numerical techniques for trajectory optimization. Numerous figures, tables. Solution guide available upon request. 1970 edition. Optimal and Robust Control Advanced Topics with MATLAB® CRC Press While there are many books on advanced control for specialists, there are few that present these topics for nonspecialists. Assuming only a basic knowledge of automatic control and signals and systems, Optimal and Robust Control: Advanced Topics with MATLAB® offers a straightforward, self-contained handbook of advanced topics and tools in automatic control. Techniques for Controlling System Performance in the Presence of Uncertainty The book deals with advanced automatic control techniques, paying particular attention to robustness—the ability to guarantee stability in the presence of uncertainty. It explains advanced techniques for handling uncertainty and optimizing the control loop. It also details analytical strategies for obtaining reduced order models. The authors then propose using the Linear Matrix Inequalities (LMI) technique as a unifying tool to solve many types of advanced control problems. Topics covered include: LQR and H-infinity approaches Kalman and singular value decomposition Open-loop balancing and reduced order models Closed-loop balancing Passive systems and bounded-real systems Criteria for stability control This easy-to-read text presents the essential theoretical background and provides numerous examples and MATLAB exercises to help the reader efficiently acquire new skills. Written for electrical, electronic, computer science, space, and automation engineers interested in automatic control, this book can also be used for self-study or for a one-semester course in robust control. Data Mining: Concepts and Techniques Elsevier Data Mining: Concepts and Techniques provides the concepts and techniques in processing gathered data or information, which will be used in various applications. Specifically, it explains data mining and the tools used in discovering knowledge from the collected data. This book is referred as the knowledge discovery from data (KDD). It focuses on the feasibility, usefulness, effectiveness, and scalability of techniques of large data sets. After describing data mining, this edition explains the methods of knowing, preprocessing, processing, and warehousing data. It then presents information about data warehouses, online analytical processing (OLAP), and data cube technology. Then, the methods involved in mining frequent patterns, associations, and correlations for

large data sets are described. The book details the methods for data classification and introduces the concepts and methods for data clustering. The remaining chapters discuss the outlier detection and the trends, applications, and research frontiers in data mining. This book is intended for Computer Science students, application developers, business professionals, and researchers who seek information on data mining. Presents dozens of algorithms and implementation examples, all in pseudo-code and suitable for use in real-world, large-scale data mining projects Addresses advanced topics such as mining object-relational databases, spatial databases, multimedia databases, time-series databases, text databases, the World Wide Web, and applications in several fields Provides a comprehensive, practical look at the concepts and techniques you need to get the most out of your data.

Modern Control Systems Modern Control Systems, 12e, is ideal for an introductory undergraduate course in control systems for engineering students. Written to be equally useful for all engineering disciplines, this text is organized around the concept of control systems theory as it has been developed in the frequency and time domains. It provides coverage of classical control, employing root locus design, frequency and response design using Bode and Nyquist plots. It also covers modern control methods based on state variable models including pole placement design techniques with full-state feedback controllers and full-state observers. Many examples throughout give students ample opportunity to apply the theory to the design and analysis of control systems. Incorporates computer-aided design and analysis using MATLAB and LabVIEW MathScript.

Feedback Control Theory for Dynamic Traffic Assignment Springer This book develops a methodology for designing feedback control laws for dynamic traffic assignment (DTA) exploiting the introduction of new sensing and information-dissemination technologies to facilitate the introduction of real-time traffic management in intelligent transportation systems. Three methods of modeling the traffic system are discussed: partial differential equations representing a distributed-parameter setting; continuous-time ordinary differential equations (ODEs) representing a continuous-time lumped-parameter setting; and discrete-time ODEs representing a discrete-time lumped-parameter setting. Feedback control formulations for reaching road-user-equilibrium are presented for each setting and advantages and disadvantage of using each are addressed. The closed-loop methods described are proposed expressly to avoid the counter-productive shifting of bottlenecks from one route to another because of driver over-reaction to routing information. The second edition of Feedback Control Theory for Dynamic Traffic Assignment has been thoroughly updated with completely new chapters: a review of the DTA problem and emphasizing real-time-feedback-based problems; an up-to-date presentation of pertinent traffic-flow theory; and a treatment of the mathematical solution to the traffic dynamics. Techniques accounting for the importance of entropy are further new inclusions at various points in the text. Researchers working in traffic control will find the theoretical material presented a sound basis for further research; the continual reference to applications will help professionals working in highway administration and engineering with the increasingly important task of maintaining and smoothing traffic flow; the extensive use of end-of-chapter exercises will help the graduate student and those new to the field to extend their knowledge.

Adaptive Control Books on Demand Adaptive control has been a remarkable field for industrial and academic research since 1950s. Since more and more adaptive algorithms are applied in various control applications, it is becoming very important for practical implementation. As it can be confirmed from the increasing number of conferences and journals on adaptive control topics, it is certain that the adaptive control is a significant guidance for technology development. The authors the chapters in this book are professionals in their areas and their recent research results are presented in this book which will also provide new ideas for improved performance of various control application problems.

Soft Computing Methods for Practical Environment Solutions: Techniques and Studies Techniques and Studies IGI Global This publication presents a series of practical applications of different Soft Computing techniques to real-world problems, showing the enormous potential of these techniques in solving problems. Provided by publisher.

Control Theory Tutorial Basic Concepts Illustrated by Software Examples Springer This open access Brief introduces the basic principles of control theory in a concise self-study guide. It complements the classic texts by emphasizing the simple conceptual unity of the subject. A novice can quickly see how and why the different parts fit together. The concepts build slowly and naturally one after another, until the reader soon has a view of the whole. Each concept is illustrated by detailed examples and graphics. The full software code for each example is available, providing the basis for experimenting with various assumptions, learning how to write programs for control analysis, and setting the stage for future research projects. The topics focus on robustness, design trade-offs, and optimality. Most of the book develops classical linear theory. The last part of the book considers robustness with respect to nonlinearity and explicitly nonlinear extensions, as well as advanced topics such as adaptive control and model predictive control. New students, as well as scientists from other backgrounds who want a concise and easy-to-grasp coverage of control theory, will benefit from the emphasis on concepts and broad understanding of the various approaches.

Mathematical Control Theory Deterministic Finite Dimensional Systems Springer Science & Business Media Geared primarily to an audience consisting of mathematically advanced undergraduate or beginning graduate students, this text may additionally be used by engineering students interested in a rigorous, proof-oriented systems course that goes beyond the classical frequency-domain material and more applied courses. The minimal mathematical background required is a working knowledge of linear algebra and differential equations. The book covers what constitutes the common core of control theory and is unique in its emphasis on foundational aspects. While covering a wide range of topics written in a standard theorem/proof style, it also develops the necessary techniques from scratch. In this second edition, new chapters and sections have been added, dealing with time optimal control of linear systems, variational and numerical approaches to nonlinear control, nonlinear controllability via Lie-algebraic methods, and controllability of recurrent nets and of linear systems with bounded controls.

Optimal Control Systems CRC Press The theory of optimal control systems has grown and flourished since the 1960's. Many texts, written on varying levels of sophistication, have been published on the subject. Yet even those purportedly designed for beginners in the field are often riddled with complex theorems, and many treatments fail to include topics that are essential to a thorough grounding in the various aspects of and approaches to optimal control. Optimal Control Systems provides a comprehensive but accessible treatment of the subject with just the right degree of mathematical rigor to be complete but practical. It provides a solid bridge between "traditional" optimization using the calculus of variations and what is called "modern" optimal control. It also treats both continuous-time and discrete-time optimal control systems, giving students a firm grasp on both methods. Among this book's most outstanding features is a summary table that accompanies each topic or problem and includes a statement of the problem with a step-by-step solution. Students will also gain valuable experience in using industry-standard MATLAB and SIMULINK software, including the Control System and Symbolic Math Toolboxes. Diverse applications across fields from power engineering to medicine make a foundation in optimal control systems an essential part of an engineer's background. This clear, streamlined presentation is ideal for a graduate level course on control

systems and as a quick reference for working engineers.

Research and Technology Program Digest Flash Index Nonlinear Oscillations, Dynamical Systems, and Bifurcations of Vector Fields Springer Science & Business Media An application of the techniques of dynamical systems and bifurcation theories to the study of nonlinear oscillations. Taking their cue from Poincare, the authors stress the geometrical and topological properties of solutions of differential equations and iterated maps. Numerous exercises, some of which require nontrivial algebraic manipulations and computer work, convey the important analytical underpinnings of problems in dynamical systems and help readers develop an intuitive feel for the properties involved.

Applied Gas Dynamics John Wiley & Sons A revised edition to applied gas dynamics with exclusive coverage on jets and additional sets of problems and examples. The revised and updated second edition of Applied Gas Dynamics offers an authoritative guide to the science of gas dynamics. Written by a noted expert on the topic, the text contains a comprehensive review of the topic; from a definition of the subject, to the three essential processes of this science: the isentropic process, shock and expansion process, and Fanno and Rayleigh flows. In this revised edition, there are additional worked examples that highlight many concepts, including moving shocks, and a section on critical Mach number is included that helps to illuminate the concept. The second edition also contains new exercise problems with the answers added. In addition, the information on ram jets is expanded with helpful worked examples. It explores the entire spectrum of the ram jet theory and includes a set of exercise problems to aid in the understanding of the theory presented. This important text: Includes a wealth of new solved examples that describe the features involved in the design of gas dynamic devices. Contains a chapter on jets; this is the first textbook material available on high-speed jets. Offers comprehensive and simultaneous coverage of both the theory and application. Includes additional information designed to help with an understanding of the material covered. Written for graduate students and advanced undergraduates in aerospace engineering and mechanical engineering.

Applied Gas Dynamics, Second Edition expands on the original edition to include not only the basic information on the science of gas dynamics but also contains information on high-speed jets.

Introduction to Applied Linear Algebra Vectors, Matrices, and Least Squares Cambridge University Press A groundbreaking introduction to vectors, matrices, and least squares for engineering applications, offering a wealth of practical examples.

The Elements of Statistical Learning Data Mining, Inference, and Prediction Springer Science & Business Media During the past decade there has been an explosion in computation and information technology. With it have come vast amounts of data in a variety of fields such as medicine, biology, finance, and marketing. The challenge of understanding these data has led to the development of new tools in the field of statistics, and spawned new areas such as data mining, machine learning, and bioinformatics. Many of these tools have common underpinnings but are often expressed with different terminology. This book describes the important ideas in these areas in a common conceptual framework. While the approach is statistical, the emphasis is on concepts rather than mathematics. Many examples are given, with a liberal use of color graphics. It should be a valuable resource for statisticians and anyone interested in data mining in science or industry. The book's coverage is broad, from supervised learning (prediction) to unsupervised learning. The many topics include neural networks, support vector machines, classification trees and boosting--the first comprehensive treatment of this topic in any book. This major new edition features many topics not covered in the original, including graphical models, random forests, ensemble methods, least angle regression & path algorithms for the lasso, non-negative matrix factorization, and spectral clustering. There is also a chapter on methods for "wide" data (p bigger than n), including multiple testing and false discovery rates. Trevor Hastie, Robert Tibshirani, and Jerome Friedman are professors of statistics at Stanford University. They are prominent researchers in this area: Hastie and Tibshirani developed generalized additive models and wrote a popular book of that title. Hastie co-developed much of the statistical modeling software and environment in R/S-PLUS and invented principal curves and surfaces. Tibshirani proposed the lasso and is co-author of the very successful An Introduction to the Bootstrap. Friedman is the co-inventor of many data-mining tools including CART, MARS, projection pursuit and gradient boosting.

The purpose of this four volume series is to make available for college teachers and students samples of important and realistic applications of mathematics which can be covered in undergraduate programs. The goal is to provide illustrations of how modern mathematics is actually employed to solve relevant contemporary problems. Although these independent chapters were prepared primarily for teachers in the general mathematical sciences, they should prove valuable to students, teachers, and research scientists in many of the fields of application as well. Prerequisites for each chapter and suggestions for the teacher are provided. Several of these chapters have been tested in a variety of classroom settings, and all have undergone extensive peer review and revision. Illustrations and exercises are included in most chapters. Some units can be covered in one class, whereas others provide sufficient material for a few weeks of class time. Volume 1 contains 23 chapters and deals with differential equations and, in the last four chapters, problems leading to partial differential equations. Applications are taken from medicine, biology, traffic systems and several other fields. The 14 chapters in Volume 2 are devoted mostly to problems arising in political science, but they also address questions appearing in sociology and ecology. Topics covered include voting systems, weighted voting, proportional representation, coalitional values, and committees. The 14 chapters in Volume 3 emphasize discrete mathematical methods such as those which arise in graph theory, combinatorics, and networks. "This publication presents a series of practical applications of different Soft Computing techniques to real-world problems, showing the enormous potential of these techniques in solving problems."--Provided by publisher.

A groundbreaking introduction to vectors, matrices, and least squares for engineering applications, offering a wealth of practical examples.

The essential introduction to the principles and applications of feedback systems--now fully revised and expanded This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of Feedback Systems is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback. Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots. Provides exercises at the end of every chapter. Comes with an elec-

tronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for researchers seeking a self-contained resource on control theory

A solutions manual to accompany An Introduction to Numerical Methods and Analysis, Second Edition An Introduction to Numerical Methods and Analysis, Second Edition reflects the latest trends in the field, includes new material and revised exercises, and offers a unique emphasis on applications. The author clearly explains how to both construct and evaluate approximations for accuracy and performance, which are key skills in a variety of fields. A wide range of higher-level methods and solutions, including new topics such as the roots of polynomials, spectral collocation, finite element ideas, and Clenshaw-Curtis quadrature, are presented from an introductory perspective, and the Second Edition also features: ulstyle="line-height: 25px; margin-left: 15px; margin-top: 0px; font-family: Arial; font-size: 13px;" Chapters and sections that begin with basic, elementary material followed by gradual coverage of more advanced material Exercises ranging from simple hand computations to challenging derivations and minor proofs to programming exercises Widespread exposure and utilization of MATLAB® An appendix that contains proofs of various theorems and other material

A revised edition to applied gas dynamics with exclusive coverage on jets and additional sets of problems and examples The revised and updated second edition of Applied Gas Dynamics offers an authoritative guide to the science of gas dynamics. Written by a noted expert on the topic, the text contains a comprehensive review of the topic; from a definition of the subject, to the three essential processes of this science: the isentropic process, shock and expansion process, and Fanno and Rayleigh flows. In this revised edition, there are additional worked examples that highlight many concepts, including moving shocks, and a section on critical Mach number is included that helps to illuminate the concept. The second edition also contains new exercise problems with the answers added. In addition, the information on ram jets is expanded with helpful worked examples. It explores the entire spectrum of the ram jet theory and includes a set of exercise problems to aid in the understanding of the theory presented. This important text: Includes a wealth of new solved examples that describe the features involved in the design of gas dynamic devices Contains a chapter on jets; this is the first textbook material available on high-speed jets Offers comprehensive and simultaneous coverage of both the theory and application Includes additional information designed to help with an understanding of the material covered Written for graduate students and advanced undergraduates in aerospace engineering and mechanical engineering, Applied Gas Dynamics, Second Edition expands on the original edition to include not only the basic information on the science of gas dynamics but also contains information on high-speed jets.

During the past decade there has been an explosion in computation and information technology. With it have come vast amounts of data in a variety of fields such as medicine, biology, finance, and marketing. The challenge of understanding these data has led to the development of new tools in the field of statistics, and spawned new areas such as data mining, machine learning, and bioinformatics. Many of these tools have common underpinnings but are often expressed with different terminology. This book describes the important ideas in these areas in a common conceptual framework. While the approach is statistical, the emphasis is on concepts rather than mathematics. Many examples are given, with a liberal use of color graphics. It should be a valuable resource for statisticians and anyone interested in data mining in science or industry. The book's coverage is broad, from supervised learning (prediction) to unsupervised learning. The many topics include neural networks, support vector machines, classification trees and boosting---the first comprehensive treatment of this topic in any book. This major new edition features many topics not covered in the original, including graphical models, random forests, ensemble methods, least angle regression & path algorithms for the lasso, non-negative matrix factorization, and spectral clustering. There is also a chapter on methods for "wide" data (p bigger than n), including multiple testing and false discovery rates. Trevor Hastie, Robert Tibshirani, and Jerome Friedman are professors of statistics at Stanford University. They are prominent researchers in this area: Hastie and Tibshirani developed generalized additive models and wrote a popular book of that title. Hastie co-developed much of the statistical modeling software and environment in R/S-PLUS and invented principal curves and surfaces. Tibshirani proposed the lasso and is co-author of the very successful An Introduction to the Bootstrap. Friedman is the co-inventor of many data-mining tools including CART, MARS, projection pursuit and gradient boosting.

Adaptive control has been a remarkable field for industrial and academic research since 1950s. Since more and more adaptive algorithms are applied in various control applications, it is becoming very important for practical implementation. As it can be confirmed from the increasing number of conferences and journals on adaptive control topics, it is certain that the adaptive control is a significant guidance for technology development. The authors the chapters in this book are professionals in their areas and their recent research results are presented in this book which will also provide new ideas for improved performance of various control application problems.

For a first-year graduate-level course on nonlinear systems. It may also be used for self-study or reference by engineers and applied mathematicians. The text is written to build the level of mathematical sophistication from chapter to chapter. It has been reorganized into four parts: Basic analysis, Analysis of feedback systems, Advanced analysis, and Nonlinear feedback control.

This open access Brief introduces the basic principles of control theory in a concise self-study guide. It complements the classic texts by emphasizing the simple conceptual unity of the subject. A novice can quickly see how and why the different parts fit together. The concepts build slowly and naturally one after another, until the reader soon has a view of the whole. Each concept is illustrated by detailed examples and graphics. The full software code for each example is available, providing the basis for experimenting with various assumptions, learning how to write programs for control analysis, and setting the stage for future research projects. The topics focus on robustness, design trade-offs, and optimality. Most of the book develops classical linear theory. The last part of the book considers robustness with respect to nonlinearity and explicitly nonlinear extensions, as well as advanced topics such as adaptive control and model predictive control. New students, as well as scientists from other backgrounds who want a concise and easy-to-grasp coverage of control theory, will benefit from the emphasis on concepts and broad understanding of the various approaches.

Geared primarily to an audience consisting of mathematically advanced undergraduate or beginning graduate students, this text may additionally be used by engineering students interested in a rigorous, proof-oriented systems course that goes beyond the classical frequency-domain material and more applied courses. The minimal mathematical background required is a working knowledge of linear algebra and differential equations. The book covers what constitutes the common core of control theory and is unique in its emphasis on foundational aspects. While covering a wide range of topics written in a standard theorem/proof style, it also develops the necessary techniques from scratch. In this second edition, new chapters and sec-

tions have been added, dealing with time optimal control of linear systems, variational and numerical approaches to nonlinear control, nonlinear controllability via Lie-algebraic methods, and controllability of recurrent nets and of linear systems with bounded controls.

This book develops a methodology for designing feedback control laws for dynamic traffic assignment (DTA) exploiting the introduction of new sensing and information-dissemination technologies to facilitate the introduction of real-time traffic management in intelligent transportation systems. Three methods of modeling the traffic system are discussed: partial differential equations representing a distributed-parameter setting; continuous-time ordinary differential equations (ODEs) representing a continuous-time lumped-parameter setting; and discrete-time ODEs representing a discrete-time lumped-parameter setting. Feedback control formulations for reaching road-user-equilibrium are presented for each setting and advantages and disadvantage of using each are addressed. The closed-loop methods described are proposed expressly to avoid the counter-productive shifting of bottlenecks from one route to another because of driver over-reaction to routing information. The second edition of Feedback Control Theory for Dynamic Traffic Assignment has been thoroughly updated with completely new chapters: a review of the DTA problem and emphasizing real-time-feedback-based problems; an up-to-date presentation of pertinent traffic-flow theory; and a treatment of the mathematical solution to the traffic dynamics. Techniques accounting for the importance of entropy are further new inclusions at various points in the text. Researchers working in traffic control will find the theoretical material presented a sound basis for further research; the continual reference to applications will help professionals working in highway administration and engineering with the increasingly important task of maintaining and smoothing traffic flow; the extensive use of end-of-chapter exercises will help the graduate student and those new to the field to extend their knowledge.

Nonlinear Dynamical Systems and Control presents and develops an extensive treatment of stability analysis and control design of nonlinear dynamical systems, with an emphasis on Lyapunov-based methods. Dynamical system theory lies at the heart of mathematical sciences and engineering. The application of dynamical systems has crossed interdisciplinary boundaries from chemistry to biochemistry to chemical kinetics, from medicine to biology to population genetics, from economics to sociology to psychology, and from physics to mechanics to engineering. The increasingly complex nature of engineering systems requiring feedback control to obtain a desired system behavior also gives rise to dynamical systems. Wassim Haddad and VijaySekhar Chellaboina provide an exhaustive treatment of nonlinear systems theory and control using the highest standards of exposition and rigor. This graduate-level textbook goes well beyond standard treatments by developing Lyapunov stability theory, partial stability, boundedness, input-to-state stability, input-output stability, finite-time stability, semistability, stability of sets and periodic orbits, and stability theorems via vector Lyapunov functions. A complete and thorough treatment of dissipativity theory, absolute stability theory, stability of feedback systems, optimal control, disturbance rejection control, and robust control for nonlinear dynamical systems is also given. This book is an indispensable resource for applied mathematicians, dynamical systems theorists, control theorists, and engineers.

This unique book presents an analytical uniform design methodology of continuous-time or discrete-time nonlinear control system design which guarantees desired transient performances in the presence of plant parameter variations and unknown external disturbances. All results are illustrated with numerical simulations, their practical importance is highlighted, and they may be used for real-time control system design in robotics, mechatronics, chemical reactors, electrical and electro-mechanical systems as well as aircraft control systems. The book is easy reading and is suitable for teaching.

Signals and Systems Using MATLAB, Third Edition, features a pedagogically rich and accessible approach to what can commonly be a mathematically dry subject. Historical notes and common mistakes combined with applications in controls, communications and signal processing help students understand and appreciate the usefulness of the techniques described in the text. This new edition features more end-of-chapter problems, new content on two-dimensional signal processing, and discussions on the state-of-the-art in signal processing. Introduces both continuous and discrete systems early, then studies each (separately) in-depth Contains an extensive set of worked examples and homework assignments, with applications for controls, communications, and signal processing Begins with a review on all the background math necessary to study the subject Includes MATLAB® applications in every chapter

This official Student Solutions Manual includes solutions to the odd-numbered exercises featured in the second edition of Steven Strogatz's classic text Nonlinear Dynamics and Chaos: With Applications to Physics, Biology, Chemistry, and Engineering. The textbook and accompanying Student Solutions Manual are aimed at newcomers to nonlinear dynamics and chaos, especially students taking a first course in the subject. Complete with graphs and worked-out solutions, this manual demonstrates techniques for students to analyze differential equations, bifurcations, chaos, fractals, and other subjects Strogatz explores in his popular book.

Data Mining: Concepts and Techniques provides the concepts and techniques in processing gathered data or information, which will be used in various applications. Specifically, it explains data mining and the tools used in discovering knowledge from the collected data. This book is referred as the knowledge discovery from data (KDD). It focuses on the feasibility, usefulness, effectiveness, and scalability of techniques of large data sets. After describing data mining, this edition explains the methods of knowing, preprocessing, processing, and warehousing data. It then presents information about data warehouses, online analytical processing (OLAP), and data cube technology. Then, the methods involved in mining frequent patterns, associations, and correlations for large data sets are described. The book details the methods for data classification and introduces the concepts and methods for data clustering. The remaining chapters discuss the outlier detection and the trends, applications, and research frontiers in data mining. This book is intended for Computer Science students, application developers, business professionals, and researchers who seek information on data mining. Presents dozens of algorithms and implementation examples, all in pseudo-code and suitable for use in real-world, large-scale data mining projects Addresses advanced topics such as mining object-relational databases, spatial databases, multimedia databases, time-series databases, text databases, the World Wide Web, and applications in several fields Provides a comprehensive, practical look at the concepts and techniques you need to get the most out of your data

This introduction to applied nonlinear dynamics and chaos places emphasis on teaching the techniques and ideas that will enable students to take specific dynamical systems and obtain some quantitative information about their behavior. The new edition has been updated and extended through-

out, and contains a detailed glossary of terms. From the reviews: "Will serve as one of the most eminent introductions to the geometric theory of dynamical systems." --*Monatshefte für Mathematik*

Upper-level undergraduate text introduces aspects of optimal control theory: dynamic programming, Pontryagin's minimum principle, and numerical techniques for trajectory optimization. Numerous figures, tables. Solution guide available upon request. 1970 edition.

An application of the techniques of dynamical systems and bifurcation theories to the study of nonlinear oscillations. Taking their cue from Poincaré, the authors stress the geometrical and topological properties of solutions of differential equations and iterated maps. Numerous exercises, some of which require nontrivial algebraic manipulations and computer work, convey the important analytical underpinnings of problems in dynamical systems and help readers develop an intuitive feel for the properties involved.

Applied Nonlinear Control Pearson Education Nonlinear Control Prentice Hall

This textbook is aimed at newcomers to nonlinear dynamics and chaos, especially students taking a first course in the subject. The presentation stresses analytical methods, concrete examples, and geometric intuition. The theory is developed systematically, starting with first-order differential equations and their bifurcations, followed by phase plane analysis, limit cycles and their bifurcations, and culminating with the Lorenz equations, chaos, iterated maps, period doubling, renormalization, fractals, and strange attractors.

Mathematics is playing an ever more important role in the physical and biological sciences, provoking a blurring of boundaries between scientific disciplines and a resurgence of interest in the modern as well as the classical techniques of applied mathematics. This renewal of interest, both in research and teaching, has led to the establishment of the series: Texts in Applied Mathematics (TAM). The development of new courses is a natural consequence of a high level of excitement over the research frontier as newer techniques, such as numerical and symbolic computer systems, dynamical systems, and chaos, mix with and reinforce the traditional methods of applied mathematics. Thus, the purpose of this textbook series is to meet the current and future needs of these advances and encourage the teaching of new courses. TAM will publish textbooks suitable for use in advanced undergraduate and beginning graduate courses, and will complement the Applied Mathematical Sciences (AMS) series, which will focus on advanced textbooks and research level monographs. Preface to the Second Edition This book covers those topics necessary for a clear understanding of the qualitative theory of ordinary differential equations and the concept of a dynamical system. It is written for advanced undergraduates and for beginning graduate students. It begins with a study of linear systems of ordinary differential equations, a topic already familiar to the student who has completed a first course in differential equations.

Differential equations are the basis for models of any physical systems that exhibit smooth change. This book combines much of the material found in a traditional course on ordinary differential equations with an introduction to the more modern theory of dynamical systems. Applications of this theory to physics, biology, chemistry, and engineering are shown through examples in such areas as population modeling, fluid dynamics, electronics, and mechanics. Differential Dynamical Systems begins with coverage of linear systems, including matrix algebra; the focus then shifts to foundational material on nonlinear differential equations, making heavy use of the contraction-mapping theorem. Subsequent chapters deal specifically with dynamical systems concepts: flow, stability, invariant manifolds, the phase plane, bifurcation, chaos, and Hamiltonian dynamics. This new edition contains several important updates and revisions throughout the book. Throughout the book, the author includes exercises to help students develop an analytical and geometrical understanding of dynamics. Many of the exercises and examples are based on applications and some involve computation; an appendix offers simple codes written in Maple, Mathematica, and MATLAB software to give students practice with computation applied to dynamical systems problems.

This textbook develops the essential tools of linear algebra, with the goal of imparting technique alongside contextual understanding. Applications go hand-in-hand with theory, each reinforcing and explaining the other. This approach encourages students to develop not only the technical proficiency needed to go on to further study, but an appreciation for when, why, and how the tools of linear algebra can be used across modern applied mathematics. Providing an extensive treatment of essential topics such as Gaussian elimination, inner products and norms, and eigenvalues and singular values, this text can be used for an in-depth first course, or an application-driven second course in linear algebra. In this second edition, applications have been updated and expanded to include numerical methods, dynamical systems, data analysis, and signal processing, while the pedagogical flow of the core material has been improved. Throughout, the text emphasizes the conceptual connections between each application and the underlying linear algebraic techniques, thereby enabling students not only to learn how to apply the mathematical tools in routine contexts, but also to understand what is required to adapt to unusual or emerging problems. No previous knowledge of linear algebra is needed to approach this text, with single-variable calculus as the only formal prerequisite. However, the reader will need to draw upon some mathematical maturity to engage in the increasing abstraction inherent to the subject. Once equipped with the main tools and concepts from this book, students will be prepared for further study in differential equations, numerical analysis, data science and statistics, and a broad range of applications. The first author's text, Introduction to Partial Differential Equations, is an ideal companion volume, forming a natural extension of the linear mathematical methods developed here.

This text presents a multi-disciplined view of optimization, providing students and researchers with a thorough examination of algorithms, methods, and tools from diverse areas of optimization without introducing excessive theoretical detail. This second edition includes additional topics, including global optimization and a real-world case study using important concepts from each chapter. Introduction to Applied Optimization is intended for ad-

vanced undergraduate and graduate students and will benefit scientists from diverse areas, including engineers.

This eagerly awaited follow-up to Nonlinear Control Systems incorporates recent advances in the design of feedback laws, for the purpose of globally stabilizing nonlinear systems via state or output feedback. The author is one of the most prominent researchers in the field.

The purpose of this book is to present a self-contained description of the fundamentals of the theory of nonlinear control systems, with special emphasis on the differential geometric approach. The book is intended as a graduate text as well as a reference to scientists and engineers involved in the analysis and design of feedback systems. The first version of this book was written in 1983, while I was teaching at the Department of Systems Science and Mathematics at Washington University in St. Louis. This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana-Champaign in 1987, at the Carl-Cranz Gesellschaft in Oberpfaffenhofen in 1987, at the University of California in Berkeley in 1988. In addition to a major rearrangement of the last two Chapters of the first version, this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985.

Modern Control Systems, 12e, is ideal for an introductory undergraduate course in control systems for engineering students. Written to be equally useful for all engineering disciplines, this text is organized around the concept of control systems theory as it has been developed in the frequency and time domains. It provides coverage of classical control, employing root locus design, frequency and response design using Bode and Nyquist plots. It also covers modern control methods based on state variable models including pole placement design techniques with full-state feedback controllers and full-state observers. Many examples throughout give students ample opportunity to apply the theory to the design and analysis of control systems. Incorporates computer-aided design and analysis using MATLAB and LabVIEW MathScript.

Fuzzy Algorithms for Control gives an overview of the research results of a number of European research groups that are active and play a leading role in the field of fuzzy modeling and control. It contains 12 chapters divided into three parts. Chapters in the first part address the position of fuzzy systems in control engineering and in the AI community. State-of-the-art surveys on fuzzy modeling and control are presented along with a critical assessment of the role of these methodologists in control engineering. The second part is concerned with several analysis and design issues in fuzzy control systems. The analytical issues addressed include the algebraic representation of fuzzy models of different types, their approximation properties, and stability analysis of fuzzy control systems. Several design aspects are addressed, including performance specification for control systems in a fuzzy decision-making framework and complexity reduction in multivariable fuzzy systems. In the third part of the book, a number of applications of fuzzy control are presented. It is shown that fuzzy control in combination with other techniques such as fuzzy data analysis is an effective approach to the control of modern processes which present many challenges for the design of control systems. One has to cope with problems such as process nonlinearity, time-varying characteristics for incomplete process knowledge. Examples of real-world industrial applications presented in this book are a blast furnace, a lime kiln and a solar plant. Other examples of challenging problems in which fuzzy logic plays an important role and which are included in this book are mobile robotics and aircraft control. The aim of this book is to address both theoretical and practical subjects in a balanced way. It will therefore be useful for readers from the academic world and also from industry who want to apply fuzzy control in practice.

The theory of optimal control systems has grown and flourished since the 1960's. Many texts, written on varying levels of sophistication, have been published on the subject. Yet even those purportedly designed for beginners in the field are often riddled with complex theorems, and many treatments fail to include topics that are essential to a thorough grounding in the various aspects of and approaches to optimal control. Optimal Control Systems provides a comprehensive but accessible treatment of the subject with just the right degree of mathematical rigor to be complete but practical. It provides a solid bridge between "traditional" optimization using the calculus of variations and what is called "modern" optimal control. It also treats both continuous-time and discrete-time optimal control systems, giving students a firm grasp on both methods. Among this book's most outstanding features is a summary table that accompanies each topic or problem and includes a statement of the problem with a step-by-step solution. Students will also gain valuable experience in using industry-standard MATLAB and SIMULINK software, including the Control System and Symbolic Math Toolboxes. Diverse applications across fields from power engineering to medicine make a foundation in optimal control systems an essential part of an engineer's background. This clear, streamlined presentation is ideal for a graduate level course on control systems and as a quick reference for working engineers.

This book introduces a comprehensive methodology for adaptive control design of parabolic partial differential equations with unknown functional parameters, including reaction-convection-diffusion systems ubiquitous in chemical, thermal, biomedical, aerospace, and energy systems. Andrey Smyshlyaev and Miroslav Krstic develop explicit feedback laws that do not require real-time solution of Riccati or other algebraic operator-valued equations. The book emphasizes stabilization by boundary control and using boundary sensing for unstable PDE systems with an infinite relative degree. The book also presents a rich collection of methods for system identification of PDEs, methods that employ Lyapunov, passivity, observer-based, swapping-based, gradient, and least-squares tools and parameterizations, among others. Including a wealth of stimulating ideas and providing the mathematical and control-systems background needed to follow the designs and proofs, the book will be of great use to students and researchers in mathematics, engineering, and physics. It also makes a valuable supplemental text for graduate courses on distributed parameter systems and adaptive control.